IN THE CLAIMS:

1. (Currently Amended) A machining device for ~~said~~ components ~~(2), especially body parts, with~~, the device comprising: a multiaxial transport means; a ~~(6) and at least one said tool (11), characterized in that at least one said~~ carrier [[(7)]] with ~~one or more said~~ a multiaxial machining unit ~~units (8, 9)~~ with a ~~plurality of said~~ tools ~~(11) are~~ arranged at ~~the~~ a transport means [[(6)]].

2. (Currently Amended) A machining device in accordance with claim 1, ~~characterized in that~~ wherein the transport means [[(6)]] is designed as a multiaxial transport robot.

3. (Currently Amended) A machining device in accordance with claim 1 ~~or 2~~, ~~characterized in that~~ wherein the machining units ~~(8, 9)~~ are designed as ~~said~~ multiaxial small robots [[(10)]] each with one of said tools.

4. (Currently Amended) A machining device in accordance with claims 1, ~~2 or 3, characterized in that~~ wherein the machining units ~~(8, 9)~~ are arranged on different sides of the carrier [[(7)]].

5. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the machining units ~~(8, 9)~~ can be controlled individually.

6. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the machining units ~~(8, 9)~~ can be controlled from the transport means [[(6)]].

7. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the carrier [[(7)]] is designed as an essentially straight girder.

8. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the small robots [[(10)]] are designed as six-axis articulated arm robots.

9. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the machining units ~~(8, 9)~~ are arranged on different sides of the carrier [[(7)]], offset in relation to one another.

10. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~characterized in that~~ wherein the machining units ~~(8, 9)~~ carry said replaceable tools [[(11)]].

11. (Currently Amended) A machining device in accordance with ~~one of the above~~

~~claims~~ claim 1, ~~**characterized in that**~~ wherein the tools [[(11)]] of the machining units ~~(8, 9)~~ are designed at least partly as said joining tools.

12. (Currently Amended) A machining device in accordance with ~~one of the above claims~~ claim 1, ~~**characterized in that**~~ wherein an additional support [[(22)]] is provided for the carrier [[(7)]].

13. A machining station ~~for machining said components (2), especially for joining said body parts, **characterized in that** one or more said machining devices (5) in accordance with one of the claims 1 through 12 above are arranged in the said machining station (1),~~ comprising:

a multiaxial robot transport;

a carrier connected to said multiaxial robot transport for movement therewith;

a plurality of multiaxial machining units carried by said carrier;

a plurality of tools, each of said multiaxial machining units being connected to a respective one of said tools.

14. (Currently Amended) A machining station in accordance with claim 13, ~~**characterized in that the**~~ wherein each machining device ~~(s) (5)~~ is[[/are]] arranged at a station frame [[(3)]].

15. (Currently Amended) A machining station in accordance with claim 13 ~~or 14~~,

~~characterized in that the~~ wherein each machining device ~~(s) (5)~~ is[[/are]] designed as a portal robot/portal robots.

16. (Currently Amended) A method of machining ~~said~~ cubic components [[(2)]], ~~especially said body parts~~, by means of a multiaxial transport means [[(6)]] and at least one ~~said~~ tool [[(11)]], ~~characterized in that~~ and further comprising the steps of: employing the transport means ~~(6) introduces~~ for introducing at least one ~~said~~ carrier [[(7)]] with one or more ~~said~~ multiaxial machining units [[(11)]] into the interior space of the component [[(2)]], wherein the machining units ~~(8, 9)~~ carry out machining operations on the inside of the component [[(2)]].

17. (Currently Amended) A method in accordance with claim 16, ~~characterized in that~~ wherein the component [[(2)]] is clamped on the inside by one or more said machining units ~~(8, 9)~~ and is machined by said other machining units ~~(8, 9)~~.

18. (Currently Amended) A method in accordance with claim 16 ~~or 17~~, ~~characterized in that~~ wherein the carrier [[(7)]] with the machining units ~~(8, 9)~~ is introduced through an opening into the component [[(2)]].

19. (Currently Amended) A method in accordance with claims 16, ~~17 or 18,~~ ~~characterized in that~~ wherein the carrier [[(7)]] with the machining units ~~(8, 9)~~ is additionally

supported in the working position by a support means [[(22)]].